Solving punctured multi black hole initial data with finite element method

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Einstein Toolkit Workshop, Stockholm

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- The indicator for the adaptive refinement
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Puncture type initial data in NR

$$R + K^2 - K_{ij}K^{ij} = 0$$
$$\nabla_i K^j{}_i - \nabla_i K = 0$$

Vacuum spacetime Involve BH only

$$\gamma_{ij} = \psi^4 f_{ij},$$

$$K_{ij} = \psi^{-2} \hat{K}_{ij},$$

$$K = 0$$

$$\begin{split} \hat{K}_{ij} &= \frac{3}{2} \sum_{I} \frac{1}{r_{I}^{2}} [2P_{(i}^{I} n_{j)}^{I} - (f_{ij} - n_{i}^{I} n_{j}^{I}) P_{I}^{k} n_{k}^{I} \\ &+ \frac{4}{r_{I}} n_{(i}^{I} \epsilon_{j)k\ell} S_{I}^{k} n_{I}^{\ell}], \end{split}$$

$$-(\partial_x^2 + \partial_y^2 + \partial_z^2)\psi = \frac{1}{8}\hat{K}^{ij}\hat{K}_{ij}\psi^{-7}$$

Approach to the black holes $(r_I \rightarrow 0)$, ψ will diverge

$$\psi \equiv 1 + \sum_{I} \frac{m_{I}}{2r_{I}} + u,$$

$$-(\partial_x^2 + \partial_y^2 + \partial_z^2)u = \frac{1}{8}\hat{K}^{ij}\hat{K}_{ij}\psi^{-7}$$

u is
$$\mathcal{C}^2$$
 at $r_I = 0$

[Brandt, Bruegman, PRL (1997)]

$$u \to 0$$
 when $r \to \infty$.

approximate Dirichlet boundary condition

$$u = d(x)$$
 at $\partial \Omega$,

with d = 0

approximate Robin boundary condition

$$\vec{n} \cdot \nabla u + \alpha(x)u = b(x)$$
 at $\partial \Omega$,

with b = 0 and $\alpha = \frac{1}{r} \frac{\partial r}{\partial n}$

Based on the assumption $u = \frac{a}{r}$, a corresponds to the monopole of the spacetime (mass)

Weak form

$$-\nabla^2 u = f(u) \text{ in } \Omega,$$

$$\begin{split} &\int_{\Omega} (\nabla u) \cdot (\nabla v) d^3 x + \int_{\partial \Omega} \alpha u v ds \\ = &\int_{\Omega} f(u) v d^3 x + \int_{\partial \Omega} b v ds. \end{split}$$

$$u = u^i \phi_i$$

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$$u^{i} \left[\int_{\Omega} (\nabla \phi_{i}) \cdot (\nabla \phi_{j}) d^{3}x + \int_{\partial \Omega} \alpha \phi_{i} \phi_{j} ds \right]$$
$$= \int_{\Omega} f(u) \phi_{j} d^{3}x + \int_{\partial \Omega} b \phi_{j} ds.$$

Use Newtonian iteration method to solve above non-linear system

$$u_{(n+1)} = u_{(n)} + \Delta u^i \phi_i$$

$$\begin{bmatrix} F'_{ij} - M_{ij} - \alpha_{ij} \end{bmatrix} \Delta u^j = \int_{\Omega} (\nabla u_{(n)}) \cdot (\nabla \phi_i) d^3 x$$
$$+ \int_{\partial \Omega} \alpha u_{(n)} \phi_i ds - \int_{\Omega} f(u_{(n)}) \phi_i d^3 x - \int_{\partial \Omega} b \phi_j ds$$

$$\begin{split} M_{ij} &= \int_{\Omega} (\nabla \phi_i) \cdot (\nabla \phi_j) d^3 x, \\ F'_{ij} &= \int_{\Omega} \frac{df}{du} (u_{(n)}) \phi_i \phi_j d^3 x, \\ \alpha_{ij} &= \int_{\partial \Omega} \alpha \phi_i \phi_j ds. \end{split}$$

PHG and CaPHG

http://lsec.cc.ac.cn/phg/download.htm



CaPHG

The goal of <u>CaPHG is to integrate Cactus with PHG</u>, an FEM library to help the application development with both FEM and DG methods on unstructure meshes. The motivation is to take advantage of the programmability of the Cactus computational framework and the performance and scalability of the PHG library to provide an integrated problem solving environment to solve large scale scientific problems on high-end computing facilities.

PHG and CaPHG

https://www.cct.lsu.edu/~jtao/cct/CaPHG/CaPHG.html

Cactus on Unstructured Meshes with CaPHG

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Cactus Parallel Hierarchical Grid

Initial mesh grid generating 1

Simplest decomposition of a box: 8 vertices and 5 elements



Initial mesh grid generating 2

Using NetGen to generate mesh grid



More uniform than previous decomposition

Initial mesh grid generating 3

Putting the puncture points on vertices



Divide the computational domain into 12 subdomains Then use NetGen to generate mesh grid

The function is C^{∞} inside of all elements

Uniform refinement

In order to avoid the pre-mature of the iteration, we need uniform refinement about 6 times and boundary refinement 3 times to resolve the whole computational domain





These two kind of norms result in roughly the same result in all of our tests

Adaptive refinement



Puncture regions can be captured automatically



It is harder to generate efficient grid for spherical boundary than for box



As expected, the boundary is farther, the numerical solutions is better



As expected, the boundary is farther, the numerical solutions is better

The convergence behaves like $\frac{1}{r_{\rm BD}}$

This confirms our assumption of Robin BD form



The spherical configuration is less accurate than the box configuration, So the numerical error is larger than that of box



No matter we put the puncture points on vertexes or not, the results are roughly the same. These plots correspond to the result we do not put the puncture points on vertexes

Resolve the whole domain





Resolve the puncture points region



Real converge process



The numerical error indicator, also the Hamiltonian constraint violation. Converging behavior near puncture points



Higher order polynomial results in more accurate solution, at the meantime the needed resolution is coarser



For the usage of finite difference code AMSS-NCKU. In practice, P1 is enough

Effect of puncture point



Requirement for the resolution is lower, while the constraint violation is smaller

The resulted solution difference is smaller than the that of polynomial order



Comparison to spectral method



The relative difference is almost uniform among the space. If the reason is resolution, we expect the spectral method is more accurate, but AFEM is more practical and more flexible, no computational cost is wasted.

Comparison to spectral method



From practical viewpoint, we use AMSS-NCKU code to compare the solutions. Although the FEM solution does not waste resolution, spectral solution is a little bit better on constraint violation

Summary and prospect

- AFEM has been applied to solve punctured multi black hole ID
- Mesh grid and boundary conditions affect the numerical solution strongly
- High order polynomial bases and/or spectral bases can be used together with AFEM to combine the advantage of FD and spectral method. But much more work is needed
- Application to the evolution of Einstein equations is appreciated. This may provide high accuracy and high parallel efficiency