

Fine

$$t = t_{n+2}$$

$$t = t_{n+1}$$

$$t_{n+\frac{1}{2}}$$

$$t = t_n$$

$$y_{n+1} = \left[\downarrow \right] + y_n$$

$$y^{(1)} = \dots k \cdot y^{(0)}$$

$$y^0 \sim t_n$$

$$y^1 \sim t_{n+\frac{1}{2}} \leftarrow$$

$$y^2 \sim t_{n+1} \leftarrow$$

$$y^3 \sim t_{n+1}$$

$$y = f(y)$$

$$\sigma = \pi$$

$$\sigma = 1$$

$$\pi = 0_{x10}$$

$$\pi = 1$$

$$\sigma_0 = 1 \sim$$



Coarse

$$k_1 = \Delta t f' + O(\Delta t^2)$$

$$k_2 = \Delta t f' + \frac{\Delta t^2}{2} y'' + \frac{\Delta t^3}{6} (y''' - f_y y'')$$

$$k_3 = \Delta t f' + \frac{\Delta t^2}{2} y'' + \frac{\Delta t^3}{6} (y''' - f_y y'') + O(\Delta t^4)$$

$$y(t) = \sum b_i(t) \tilde{k}_i$$

$$y'(t) = \sum b'_i(t) \tilde{k}_i \quad y'(t) = t, y$$

$$P(x; A) + P(x; B) \stackrel{?}{=} P(x; A+B)$$

$$y_{n+1} = y_n + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4)$$

$$k_1 = \Delta t f(t_n, y_n)$$

$$k_2 = \Delta t f(t_n + \frac{1}{2}\Delta t, y_n + \frac{1}{2}k_1)$$

$$k_3 = \Delta t f(t_n + \frac{1}{2}\Delta t, y_n + k_2)$$

$$k_4 = \Delta t f(t_n + \Delta t, y_n + k_3)$$

1. Disable prolongation of state vector
2. Interpolate \tilde{k}_i from coarser grid
3. Regular RK4 for internal points (efficient)
4. Construct y', y'', \dots with dense interpolant
5. Recompute k_i/f with (1)
6. Do RK4 of boundary points.
7. Reenable prolongation of state vector.